



中山大學
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Compilation Principle 编译原理

第18讲：中间代码(2)

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Review Questions

- What is IR (specifically, the low-level IR)?

Intermediate Representation. A machine- and language-independent version of the original source code.

- Why do we use IR?

Clean separation of front- and back-end; easy to optimize and extend

- What is three-address code (TAC)?

A type of IR, with at most three operands. (High-level assembly)

- TAC of $x + y * z + 5$?

$t_1 = y * z; t_2 = x + t_1; t_3 = t_2 + 5;$

- Possible ways to implement TAC?

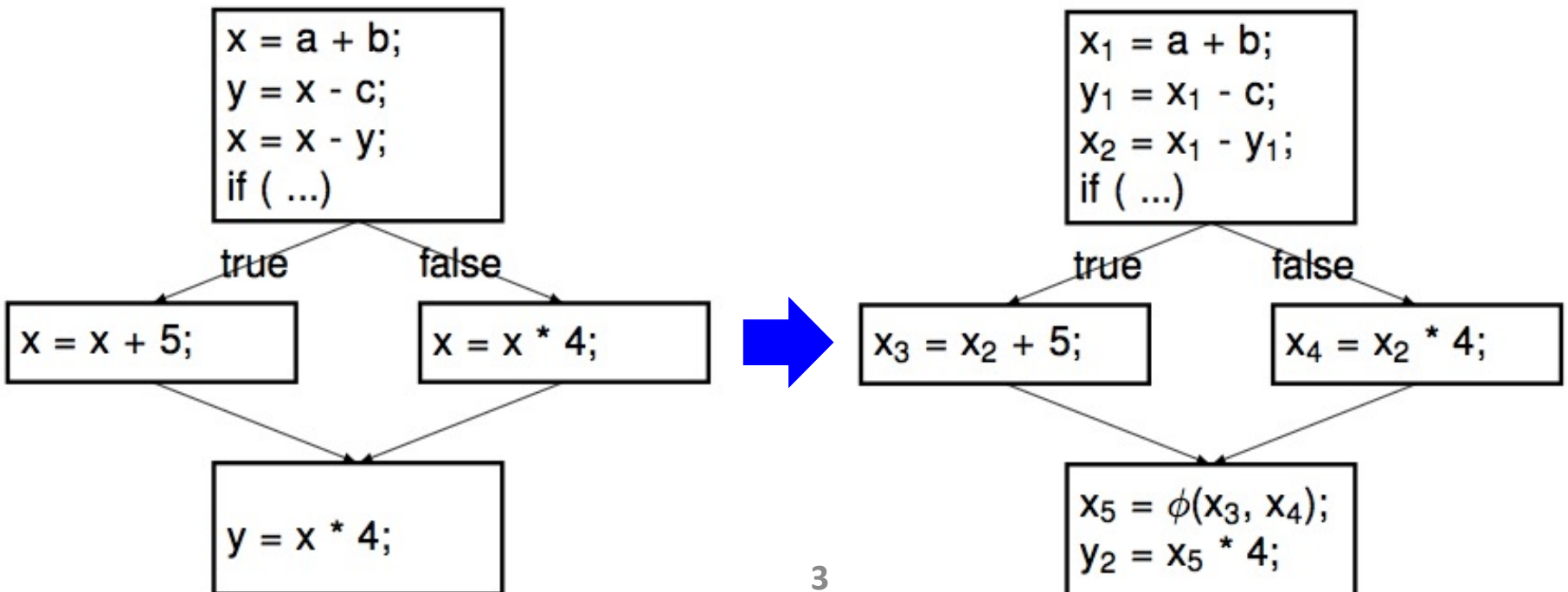
Quadruples: op arg1, arg2, result

Triples: op arg1 arg2

Indirect triples: op arg1 arg2

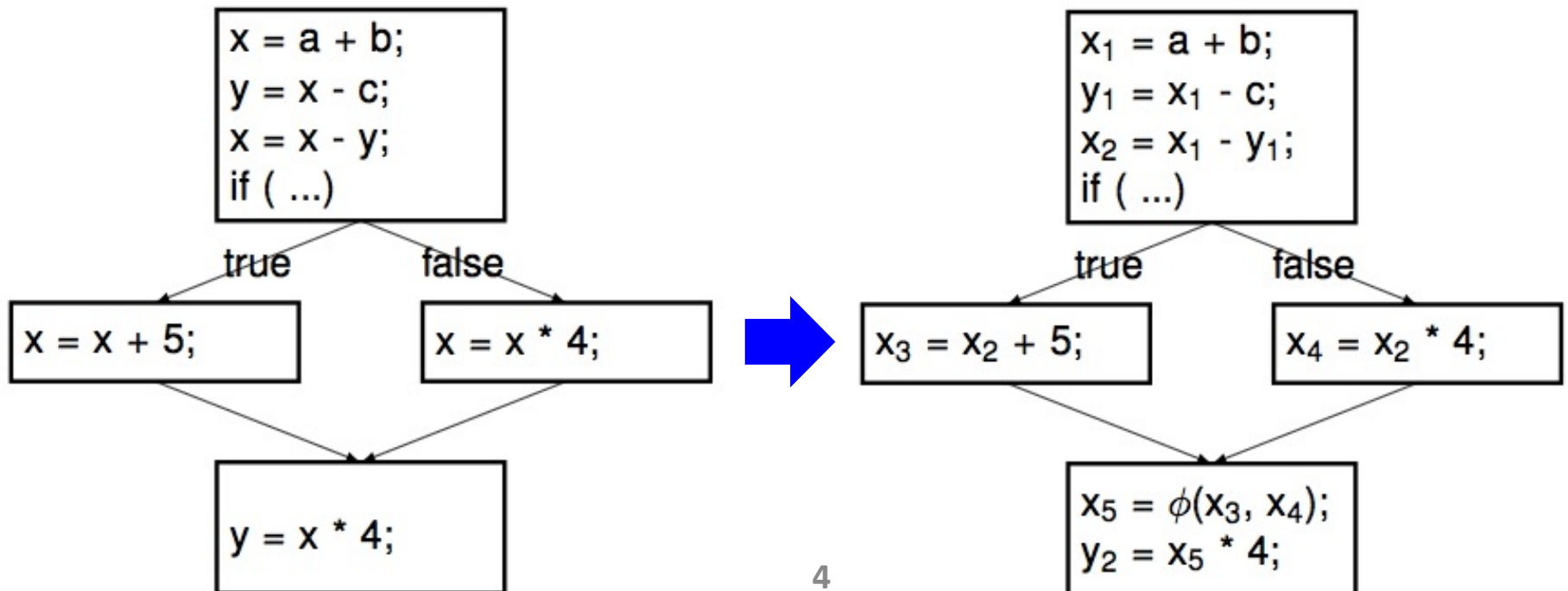
Single Static Assignment[静态单赋值]

- Every variable is assigned to exactly once statically[仅一次]
 - Give variable a different version name on every assignment
 - e.g. $x \rightarrow x_1, x_2, \dots, x_5$ for each static assignment of x
 - Now value of each variable guaranteed not to change
 - On a control flow merge, ϕ -function combines two versions
 - e.g. $x_5 = \phi(x_3, x_4)$: means x_5 is either x_3 or x_4



Benefits of SSA

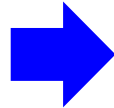
- SSA is an IR that facilitates certain code optimizations
 - SSA tells you when an optimization **shouldn't** happen
 - Suppose compiler performs CSE on previous example:
 - Without SSA, (incorrectly) tempted to eliminate second $x * 4$
 - $x = x * 4; y = x * 4; \rightarrow x = x * 4; y = x;$
 - With SSA, $x_2 * 4$ and $x_5 * 4$ are clearly different values



Benefits of SSA (cont.)

- SSA is an IR that facilitates certain code optimizations
 - SSA tells you when an optimization **should** happen
 - Suppose compiler performs dead code elimination (DCE): (DCE removes code that computes dead values)

```
x = a + b;  
x = c - d;  
y = x * b;
```



```
x1 = a + b;  
x2 = c - d;  
y1 = x2 * b;
```

- Without SSA, not very clear whether there are dead values
- With SSA, x_1 is never used and clearly a dead value
- Why does SSA work so well with compiler optimizations?
 - SSA makes flow of values explicit in the IR
 - Without SSA, need a separate dataflow graph
 - Will discuss more in **Compiler Optimization** section

SSA Orthogonal to IR Impl.[正交关系]

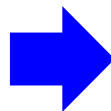
- SSA is expressed most commonly as TACs
- We learned 3 ways to implement TACs
 - quadruples
 - triples
 - indirect triples
- How you implement is orthogonal to SSA representation
 - After variable renaming, any 3-address code becomes SSA
- SSA is used widely in modern compilers:
 - GCC (GNU C Compiler)
 - LLVM Compiler
 - Oracle Java JIT Compiler
 - Google Chrome JavaScript JIT Compiler
 - PyPy Python JIT Compiler

LLVM: SSA and Phi



- All LLVM instructions are represented in the Static Single Assignment (SSA) form
 - Affordable to the design of simpler algorithms for existing optimizations and has facilitated the development of new ones
- The ‘phi’ instruction is used to implement the ϕ node in the SSA graph representing the function
 - `<result> = phi [fast-math-flags] <ty> [<val0>, <label0>], ...`
 - At runtime, the ‘phi’ instruction logically takes on the value specified by the pair corresponding to the predecessor basic block that executed just prior to the current block

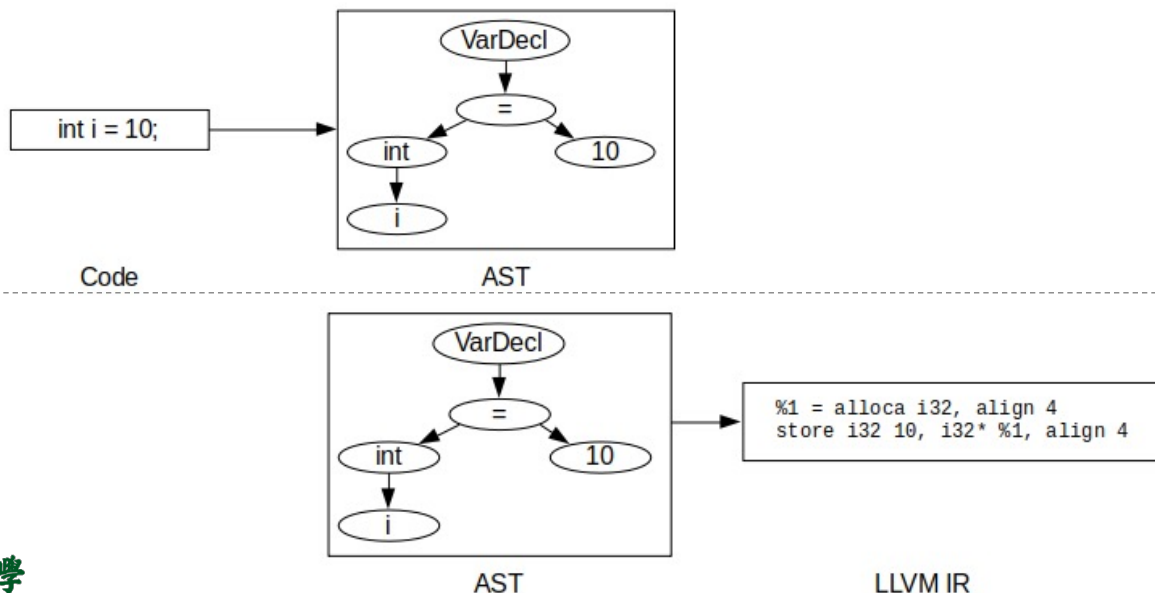
```
a = 1;  
if (v < 10)  
    a = 2;  
b = a;
```



```
a1 = 1;  
if (v < 10)  
    a2 = 2;  
b = PHI(a1, a2);
```

Generating Code: AST to IR[IR生成]

- By now, we have
 - An AST, annotated with scope and type information
- To generate three-address codes (TACs)
 - Traversing the AST after the parse[单独遍历]
 - Writing a codeGen method for the appropriate kinds of AST nodes
 - Syntax-directed translation[语法制导]
 - Generating code while parsing



Syntax Directed Translation[语法制导翻译]

- Syntax directed translation can be used again for code generation[代码生成]
 - Since code generation is also dependent on syntax/AST
 - Code generation is translating syntactic structures to code
- What language structures do we need to translate?[翻译]
 - Definitions (variables, functions, ...)
 - Assignment statements
 - Control flow statements (if-then-else, for-loop, ...)
 - ...
- We are going to use the following strategy:
 - Specify SDD semantic rules (without ordering)
 - Convert SDD rules to SDT actions (with ordering)
 - In the process, we will discover SDD has non-*L-attributes*
 - We will also discuss what to do with those non-*L-attributes*

Code Generation Overview[代码生成]

- Program code is a collection of functions
 - By now, all functions are listed in symbol table
- Goal is to generate code for each function in that list
- Generating code for a function involves two steps:
 - Processing variable definitions[变量定义]
 - Involves laying out variables in memory
 - Processing statements[语句]
 - Involves generating instructions for statements
 - Assignment[赋值]
 - Array references[数组引用]
 - Boolean expressions[布尔表达式]
 - Control-flow statements[控制流语句]
 - ...
- We will start with processing variable definitions

Processing Variable Definitions[变量定义]

- To lay out a variable, both **location** and **width** are needed
 - Location: where variable is located in memory
 - Width: how much space variable takes up in memory
- Attributes for variable definition:
 - **T V** e.g. int x;
 - **T**: non-terminal for type name
 - **T.type**: type (int, float, ...)
 - **T.width**: width of type in bytes (e.g. 4 for int)
 - **V**: non-terminal for variable name
 - **V.type**: type (int, float, ...)
 - **V.width**: width of variable according to type
 - **V.offset**: offset of variable in memory
 - But offset from what...?

Calculate Variable Location from Offset

- Naive method: reserve a big memory section for all data
 - Size data section to be large enough to contain all variables
 - Location = var offset + base of data section
- Naive method wastes a lot of memory
 - Vars with limited scope need to live only briefly in memory
 - E.g. function variables need to last only for duration of call
- **Solution:** allocate memory briefly for each scope[域内]
 - Allocate when entering scope, free when exiting scope
 - Variables in the same scope are allocated / freed together
 - Location = var offset + base of scope memory section
 - Will discuss more later in **Runtime Management**

Storage Layout of Variables in a Function

- When there are multiple variables defined in a function,
 - Compiler lays out variables in memory sequentially
 - Current offset used to place variable x in memory
 - $\text{address}(x) \leftarrow \text{offset}$
 - $\text{offset} += \text{sizeof}(x.\text{type})$

```
void foo() {  
    int a;  
    int b;  
    long long c;  
    int d;  
}
```

Address

0x0000

a

Offset = 0

Addr(a) \leftarrow 0

0x0004

b

Offset = 4

Addr(b) \leftarrow 4

0x0008

c

Offset = 8

Addr(c) \leftarrow 8

0x000c

c

0x0010

d

Offset = 16

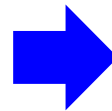
Addr(d) \leftarrow 16

Offset = 20

More about Storage Layout

- Allocation alignment[对齐]
 - Enforce $\text{addr}(x) \% \text{sizeof}(x.\text{type}) == 0$
 - Most machine architectures are designed such that computation is most efficient at sizeof(x.type) boundaries
 - E.g. most machines are designed to load integer values at integer word boundaries
 - If not on word boundary, need to load two words and shift & concatenate → inefficient

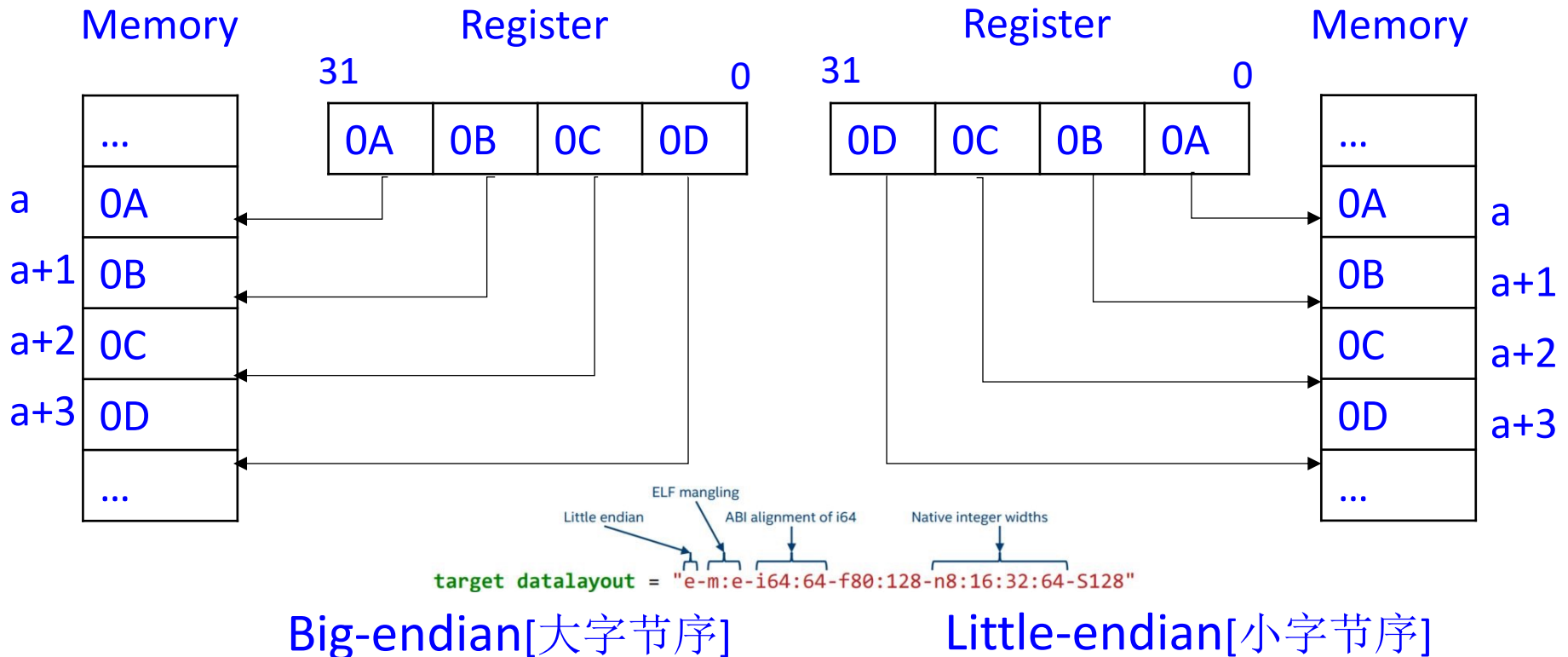
```
void foo() {  
    char a;      // addr(a) = 0  
    int b;       // addr(b) = 1  
    int c;       // addr(c) = 5  
    long long d; // addr(d) = 9  
}
```



```
void foo() {  
    char a;      // addr(a) = 0  
    int b;       // addr(b) = 4  
    int c;       // addr(c) = 8  
    long long d; // addr(d) = 16  
}
```

More about Storage Layout (cont.)

- Endianness[字节序]
 - Big endian: MSB (most significant byte) in lowest address
 - Little endian: LSB (least significant byte) in lowest address



Type Expressions[类型表达式]

- A **type expression** is either a basic type or is formed by applying an operator called a *type constructor*[类型构造符] to a type expression
 - Basic type: *integer, float, char, Boolean, void*
 - Array: *array(l, T)* is a type expression, if *T* is
 - $\text{int}[3] \leftrightarrow \text{array}(3, \text{int})$
 - $\text{int}[2][3] \leftrightarrow \text{array}(2, \text{array}(3, \text{int}))$
 - Pointer: *pointer(T)* is a type expression, if *T* is
 - $\text{int} * \text{val} \leftrightarrow \text{pointer}(\text{int})$

```
P -> D
D -> T id; D1 | ε
T -> B C | *T1
B -> int | real
C -> [num]C1 | ε
```


CodeGen: Variable Definitions

- Translating variable definitions

- *enter(name, type, offset)*

- Save the type and relative address in the symbol-table entry for the name

① $P \rightarrow \{ \text{offset} = 0 \} D$

② $D \rightarrow T \text{ id}; \{ \text{enter}(\text{id.lexeme}, T.\text{type}, \text{offset});$
 $\text{offset} = \text{offset} + T.\text{width}; \} D_1$

③ $D \rightarrow \varepsilon$

④ $T \rightarrow B \{ t = B.\text{type}; w = B.\text{width}; \}$
 $C \{ T.\text{type} = C.\text{type}; T.\text{width} = C.\text{width}; \}$

⑤ $T \rightarrow *T_1 \{ T.\text{type} = \text{pointer}(T_1.\text{type}); T.\text{width} = 4; \}$

⑥ $B \rightarrow \text{int} \{ B.\text{type} = \text{int}; B.\text{width} = 4; \}$

⑦ $B \rightarrow \text{real} \{ B.\text{type} = \text{real}; B.\text{width} = 8; \}$

⑧ $C \rightarrow \varepsilon \{ C.\text{type} = t; C.\text{width} = w; \}$

⑨ $C \rightarrow [\text{num}]C_1 \{ C.\text{type} = \text{array}(\text{num.val}, C_1.\text{type});$
 $C.\text{width} = \text{num.val} * C_1.\text{width}; \}$

- Examples:

- *real x; int i;*

- *int[2][3];*

- *type, width*

- Syn attributes

- *t, w*

- Vars to pass type and width from B node to the node for $C \rightarrow \varepsilon$

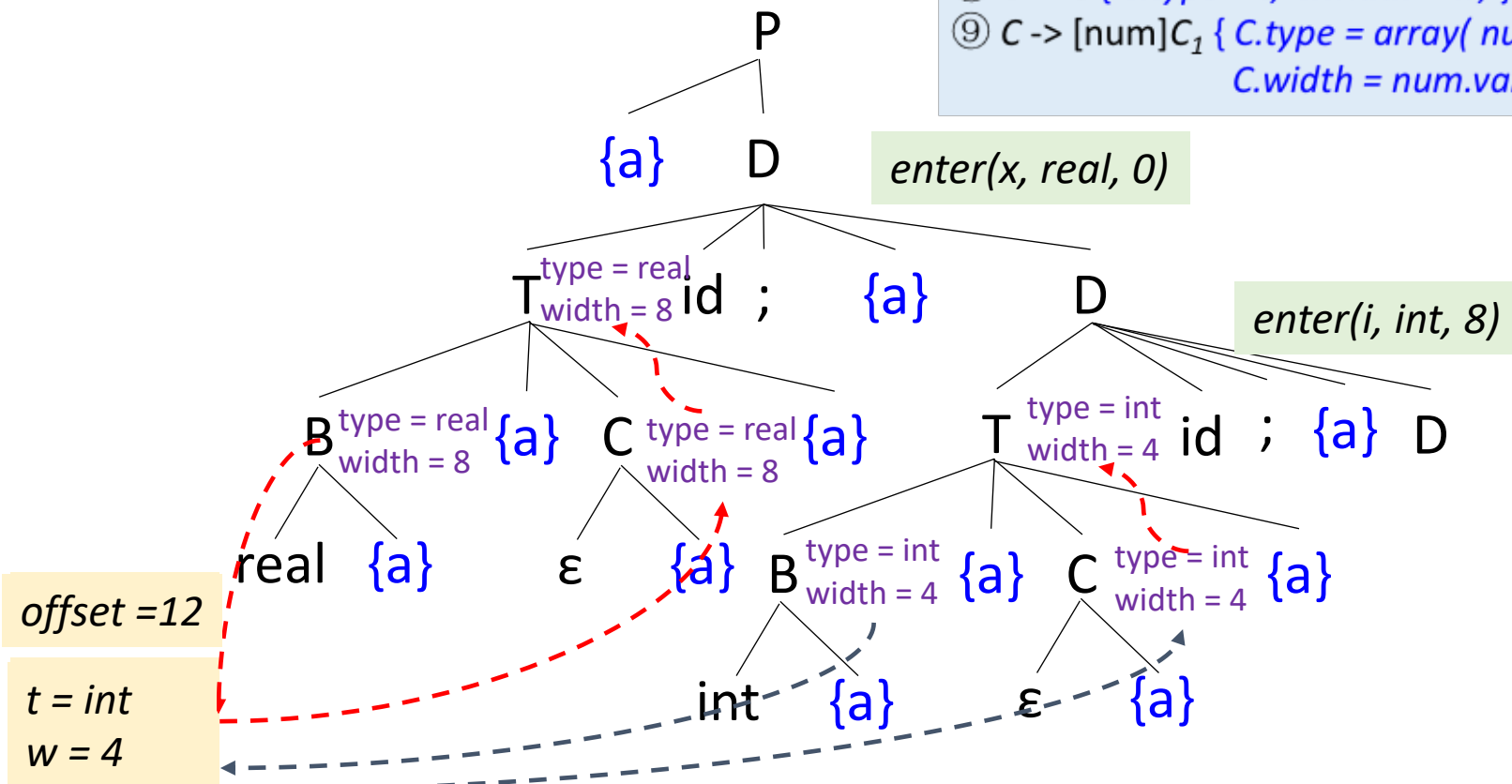
- *offset*

- The next relative address

Example

- Input: `real x; int i;`

- ① $P \rightarrow \{ \text{offset} = 0 \} D$
- ② $D \rightarrow T \text{ id}; \{ \text{enter}(\text{id.lexeme}, T.\text{type}, \text{offset}); \text{offset} = \text{offset} + T.\text{width}; \} D_1$
- ③ $D \rightarrow \epsilon$
- ④ $T \rightarrow B \{ t = B.\text{type}; w = B.\text{width}; \} C \{ T.\text{type} = C.\text{type}; T.\text{width} = C.\text{width}; \}$
- ⑤ $T \rightarrow *T_1 \{ T.\text{type} = \text{pointer}(T_1.\text{type}); T.\text{width} = 4; \}$
- ⑥ $B \rightarrow \text{int} \{ B.\text{type} = \text{int}; B.\text{width} = 4; \}$
- ⑦ $B \rightarrow \text{real} \{ B.\text{type} = \text{real}; B.\text{width} = 8; \}$
- ⑧ $C \rightarrow \epsilon \{ C.\text{type} = t; C.\text{width} = w; \}$
- ⑨ $C \rightarrow [\text{num}]C_1 \{ C.\text{type} = \text{array}(\text{num.val}, C_1.\text{type}); C.\text{width} = \text{num.val} * C_1.\text{width}; \}$



Code Generation[代码生成]

- We will use the syntax-directed formalisms to specify translation
 - Variable definitions[变量定义]
 - Assignment[赋值]
 - Array references[数组引用]
 - Boolean expressions[布尔表达式]
 - Control-flow statements[控制流语句]
- To generate three-address codes (TACs)
 - Lay out variables in memory
 - Generate TAC for any subexpressions or substatements
 - Using the result, generate TAC for the overall expression

CodeGen: Assignment Statement

- Translate into three-address code[赋值语句]
 - An expression with more than one operator will be translated into instructions with at most one operator per instruction
- Helper functions in translation
 - *lookup(id)*: search *id* in symbol table, return null if none
 - *emit()/gen()*: generate three-address IR
 - *newtemp()*: get a new temporary location

- ① $S \rightarrow id = E;$
- ② $E \rightarrow E_1 + E_2;$
- ③ $E \rightarrow - E_1$
- ④ $E \rightarrow (E_1)$
- ⑤ $E \rightarrow id$

Assignment statement:

$a = b + (-c)$

Three-address code:

$t_1 = \text{minus } c$

$t_2 = b + t_1$

$a = t_2$

SDT Translation of Assignment

- Attributes ***code*** and ***addr***

- *S.code* and *E.code* denote the TAC for *S* and *E*, respectively
- *E.addr* denotes the address that will hold the value of *E* (can be a name, constant, or a compiler-generated temporary)

- ① $S \rightarrow id = E; \{ p = lookup(id.lexeme); \text{if } !p \text{ then error};$
 $S.code = E.code \parallel$
 $gen(p '=' E.addr); \}$
- ② $E \rightarrow E_1 + E_2; \{ E.addr = newtemp();$
 $E.code = E_1.code \parallel E_2.code \parallel$
 $gen(E.addr '=' E_1.addr '+' E_2.addr); \}$
- ③ $E \rightarrow - E_1 \{ E.addr = newtemp();$
 $E.code = E_1.code \parallel$
 $gen(E.addr '=' 'minus' E_1.addr); \}$
- ④ $E \rightarrow (E_1) \{ E.addr = E_1.addr;$
 $E.code = E_1.code; \}$
- ⑤ $E \rightarrow id \{ E.addr = lookup(id.lexeme); \text{if } !E.addr \text{ then error};$
 $E.code = ''; \}$

Incremental Translation[增量翻译]

- Generate only the new three-address instructions
 - *gen()* not only constructs a three-address inst, it appends the inst to the sequence of insts generated so far

① $S \rightarrow id = E; \{ p = lookup(id.lexeme); \text{if } !p \text{ then error};$

$gen(p := E.addr); \}$

② $E \rightarrow E_1 + E_2; \{ E.addr = newtemp();$

$gen(E.addr := E_1.addr + E_2.addr); \}$

③ $E \rightarrow - E_1 \{ E.addr = newtemp();$

$gen(E.addr := 'minus' E_1.addr); \}$

④ $E \rightarrow (E_1) \{ E.addr = E_1.addr;$
 $\}$

⑤ $E \rightarrow id \{ E.addr = lookup(id.lexeme); \text{if } !E.addr \text{ then error};$
 $\}$

Code attributes can
be long strings

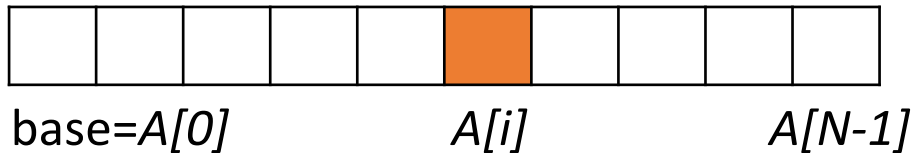
CodeGen: Array Reference [数组引用]

- Primary problem in generating code for array references is to determine the address of element

- 1D array

```
int A[N];
```

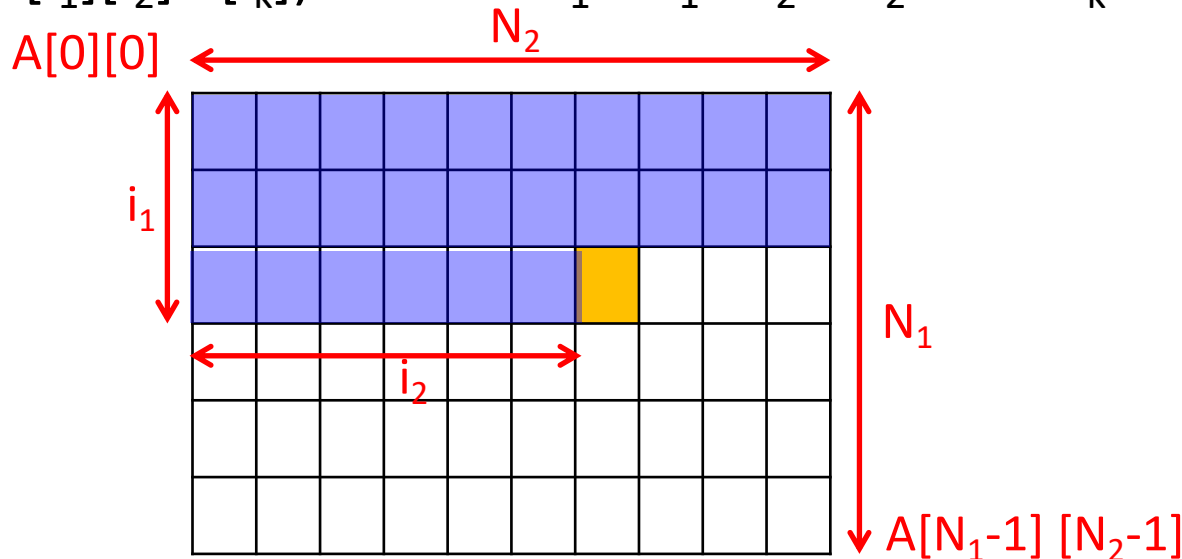
```
A[i] ++;
```



- *base*: address of the first element
 - *width*: width of each element
 - $i \times \text{width}$ is the offset
- Addressing an array element
 - $\text{addr}(A[i]) = \text{base} + i \times \text{width}$

N-dimensional Array

- Laying out 2D array in 1D memory
 - `int A[N1][N2]; /* int A[0..N1][0..N2] */`
 - `A[i1][i2] ++;`
- The organization can be row-major or column-major
 - C language uses row major (i.e., stored row by row)
 - Row-major: $\text{addr}(A[i_1, i_2]) = \text{base} + (i_1 \times \frac{N_2 * \text{width}}{W_1} + i_2 \times \frac{\text{width}}{W_2})$
- *k*-dimensional array
 - $\text{addr}(A[i_1][i_2] \dots [i_k]) = \text{base} + i_1 \times w_1 + i_2 \times w_2 + \dots + i_k \times w_k$



Translation of Array References

- Type(a) = array(10, int)
– c = a[i];

$$\text{addr}(a[i]) = \text{base} + i * 4$$

$$\begin{aligned}t_1 &= i * 4 \\t_2 &= a[t_1] \\c &= t_2\end{aligned}$$

$$\text{addr}(a[i_1][i_2]) = \text{base} + i_1 * 20 + i_2 * 4$$

- Type(a) = array(3, array(5, int))
– c = a[i₁][i₂];

$$\begin{aligned}t_1 &= i_1 * 20 \\t_2 &= i_2 * 4 \\t_3 &= t_1 + t_2 \\t_4 &= a[t_3] \\c &= t_4\end{aligned}$$

- Type(a) = array(3, array(5, array(8, int)))
– c = a[i₁][i₂][i₃]

$$\begin{aligned}\text{addr}(a[i_1][i_2][i_3]) &= \text{base} + i_1 * w_1 + i_2 * w_2 + i_3 * w_3 \\&= \text{base} + i_1 * 160 + i_2 * 32 + i_3 * 4\end{aligned}$$

Translation of Array References (cont.)

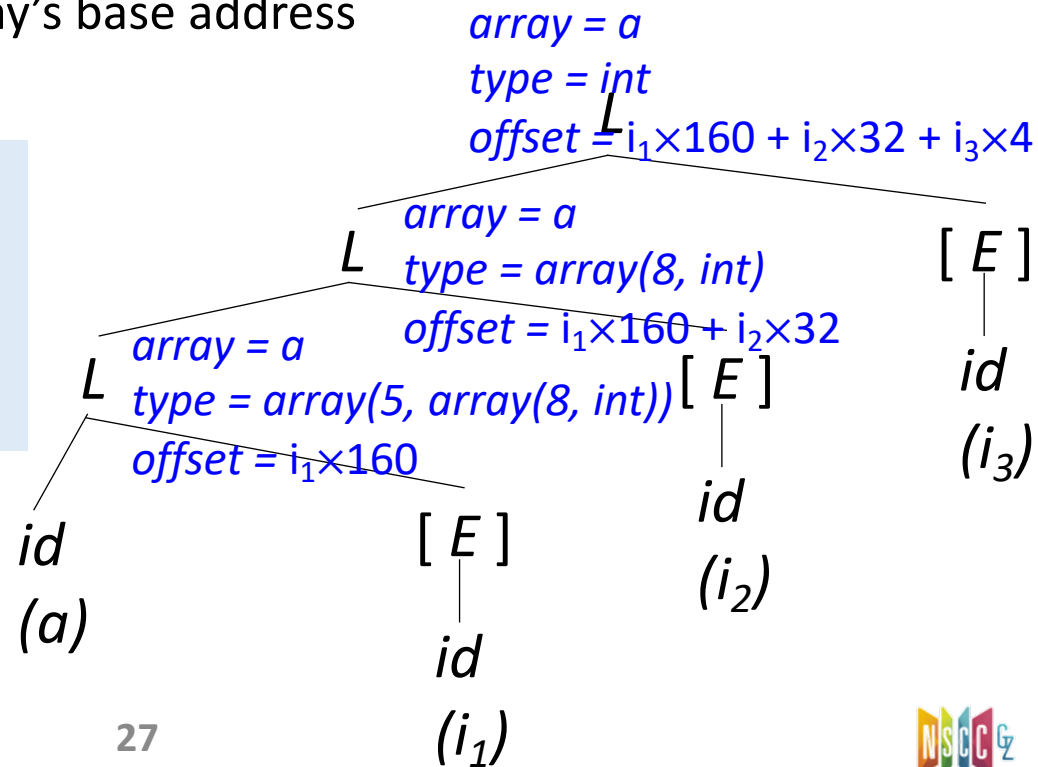
- $A[i_1][i_2][i_3]$, $\text{type}(a) = \text{array}(3, \text{array}(5, \text{array}(8, \text{int})))$
 - $L.type$: the type of the subarray generated by L
 - $L.addr$: a temporary that is used while computing the offset for the array reference by summing the terms $i_j \times w_j$
 - $L.array$: a pointer to the symbol-table entry for the array name
 - $L.array.base$ gives the array's base address

① $S \rightarrow id = E; \mid L = E;$

② $E \rightarrow E_1 + E_2 \mid - E_1 \mid (E_1) \mid id \mid L$

③ $L \rightarrow id [E] \mid L_1 [E]$

$base + i_1 \times W_1 + i_2 \times W_2 + \dots + i_k \times W_k$



Translation of Array References (cont.)

- $A[i_1][i_2][i_3]$, $\text{type}(a) = \text{array}(3, \text{array}(5, \text{array}(8, \text{int})))$

```
①  $S \rightarrow id = E; \mid L = E; \{ \text{gen}(L.array.base['L.addr']) = E.addr; \}$   
②  $E \rightarrow E_1 + E_2 \mid - E_1 \mid (E_1) \mid id \mid L \{ E.addr = \text{newtemp}();$   
    $\text{gen}(E.addr = L.array.base['L.addr']); \}$   
③  $L \rightarrow id [E] \{ L.array = \text{lookup}(id.lexeme); \text{if } !L.array \text{ then error};$   
    $L.type = L.array.type.elem;$   
    $L.offset = \text{newtemp}();$   
    $\text{gen}(L.addr = E.addr * L.type.width); \}$   
 $\mid L_1 [E] \{ L.array = L_1.array;$   
    $L.type = L_1.type.elem;$   
    $t = \text{newtemp}();$   
    $\text{gen}(t = E.addr * L.type.width);$   
    $L.addr = \text{newtemp}();$   
    $\text{gen}(L.addr = L_1.addr + t; \}$ 
```

```
 $t_1 = i_1 * 160$   
 $t_2 = i_2 * 32$   
 $t_3 = t_1 + t_2$   
 $t_4 = i_3 * 4$   
 $t_5 = t_3 + t_4$   
 $c = a[t_5]$ 
```

CodeGen: Boolean Expressions

- Boolean expression: $a \text{ op } b$
 - where op can be $<$, $<=$, $=$, $!=$, $>$ or $>=$, $\&\&$, $||$, ...
- **Short-circuit** evaluation[短路计算]: to skip evaluation of the rest of a boolean expression once a boolean value is known
 - Given following C code: $\text{if } (flag \ || \ foo()) \ \{ \ bar(); \};$
 - If $flag$ is true, $foo()$ never executes
 - Equivalent to: $\text{if } (flag) \ \{ \ bar(); \} \ \text{else if } (foo()) \ \{ \ bar(); \};$
 - Given following C code: $\text{if } (flag \ \&\& \ foo()) \ \{ \ bar(); \};$
 - If $flag$ is false, $foo()$ never executes
 - Equivalent to: $\text{if } (!flag) \ \{ \} \ \text{else if } (foo()) \ \{ \ bar(); \};$
 - Used to alter control flow, or compute logical values
 - Examples: $\text{if } (x < 5) \ x = 1; \ x = true; \ x = a < b$
 - For control flow, boolean operators translate to **jump** statements

Boolean Exprs (w/o Short-Circuiting)

- Computed just like any other arithmetic expression

$E \rightarrow (a < b) \text{ or } (c < d \text{ and } e < f)$

$t_1 = a < b$

$t_2 = c < d$

$t_3 = e < f$

$t_4 = t_2 \ \&\& \ t_3$

$t_5 = t_1 \ || \ t_4$

- Then, used in control-flow statements

– *S.next*: label for code generated after *S*

$S \rightarrow \text{if } E \ S_1$

if (! t_5) goto *S.next*

S_1 .code

S.next: ...

Boolean Exprs (w/ Short-Circuiting)

- Implemented via a series of jumps[利用跳转]
 - Each relational op converted to two gotos (*true* and *false*)
 - Remaining evaluation skipped when result known in middle
- Example
 - *E.true*: label for code to execute when *E* is 'true'
 - *E.false*: label for code to execute when *E* is 'false'
 - E.g. if above is condition for a *while* loop
 - *E.true* would be label at beginning of loop body
 - *E.false* would be label for code after the loop

$E \rightarrow (a < b) \text{ or } (c < d \text{ and } e < f)$

```
if (a < b) goto E.true
goto L1
L1: if (c < d) goto L2
      goto E.false
L2: if (e < f) goto E.true
      goto E.false
```

E为真: 只要a < b真

a < b假: 继续评估

a < b假、c < d真: 继续评估

E为假: a < b假, c < d假

E为真: a < b假, c < d真, e < f真

E为假: a < b假, c < d真, e < f假